Motion control Lexium 23 Plus

Catalogue

April 2012





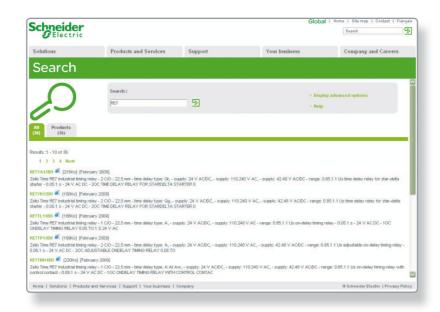




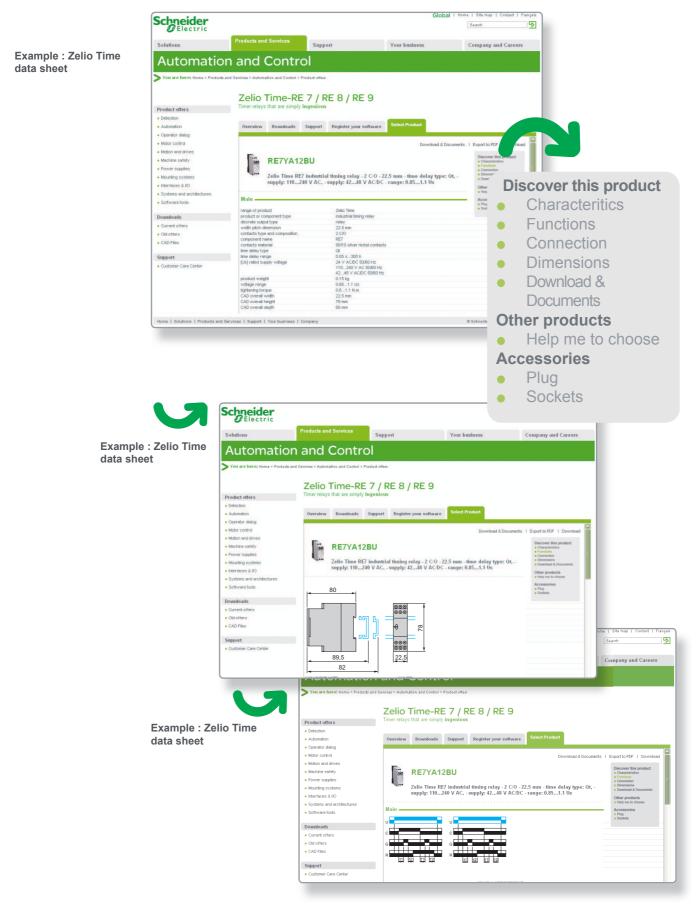
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Schneider Gelectric



Motion control Lexium 23 Plus

Lexium 23 Plus servo drives

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BCH servo motors

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Presentation

Motion control Lexium 23 Plus Servo drives



Packaging application



Woodworking application

Textile application

Presentation

The Lexium 23 Plus offer features a range of servo drives and a range of BCH servo motors.

There are a large number of possible combinations to suit the requirements of motion control applications and optimize the performance of the installation.

The servo drives range covers a wide range of power ratings from 0.1 kW to 7.5 kW, with two types of power supply:

- 200...255 V single phase, 0.1 kW to 1.5 kW
- 170...255 V three-phase, 0.1 kW to 7.5 kW

BCH motors provide a nominal torque from 0.3 Nm to 48 Nm and a nominal speed of between 1000 rpm and 3000 rpm, depending on the model. They are suitable for a very wide variety of applications due to the four levels of inertia offered (see page 14).

An offer to boost performance

When used with BCH servo motors and with the addition of options and accessories, Lexium 23 Plus servo drives provide a complete, very high performance system, designed in particular for installations equipped with simple machines. See page 8.

Compact range

The compact dimensions of Lexium 23 Plus servo drives mean they fit very easily into small spaces, thus reducing the size of the installation and the cost of the equipment.

Simple commissioning

Commissioning is simple with the Lexium 23 CT PC commissioning software which has an auto-tuning function enabling extremely fast start-up. The simplicity of the wiring of Lexium 23 Plus servo drives also makes installation easier and reduces installation costs.

Flexibility

Lexium 23 Plus servo drives have digital and analog I/O as standard, and one of the following communication interfaces, depending on the model:

- Interface for CANopen/CANmotion machine bus (LXM 23A)
- Pulse/direction (P/D) interface (LXM 23D)

The servo drives incorporate numerous functions, including auto-tuning, position, speed and torque control, etc. (see page 7).

This open communication concept enables integration into numerous different control system architectures.

Applications

- Material handling (conveying, palletizers, warehousing, etc.)
- Assembly (clamping, etc.)
- Printing
- Packaging
- Winding and unwinding
- Machine tools (multi-axis machines, cutting machines, etc.)
- Etc.

Motion control Lexium 23 Plus Servo drives

The Lexium 23 Plus servo drive range

Configuration

The drives can be configured via the integrated graphic display terminal or using the Lexium 23 CT PC commissioning software.

Control

Control via CANopen machine bus: Lexium 23A servo drive

The Lexium 23 A servo drive features a CANopen/CANmotion machine bus control interface.

It also has numerous I/O:

2 inputs for high performance position capture

- 8 digital inputs
- 4 digital outputs
- 2 analog inputs
- 2 analog outputs

It has a closed loop current regulation function (sampling time 62.5 µs).

It is compatible with PLCopen function blocks which offer applications such as flying shear, rotary knife, etc.



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Lexium 23D Plus servo drives with control via I/O

Lexium 23A Plus servo drives with control via

CANopen machine bus

Control via I/O: Lexium 23D servo drive

The Lexium 23 D drive can be used in standalone operation, with no axis controller (control via digital I/O).

It can also be used with an axis controller and can therefore be incorporated in numerous architectures.

It provides, for example, the following features:

- Creation of position registers up to 8 positions
- Switching between the speed/position/torque parameters

It has a closed loop current regulation function (sampling time $62.5 \ \mu$ s).

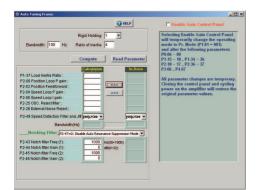
It also has a pulse/direction interface (up to 4 m/s) as well as numerous I/O:

- 8 digital inputs
- 4 digital outputs
- 2 analog inputs
- 2 analog outputs

Options:	Motor starters:	BCH servo motors:	
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Presentation (continued)

Motion control Lexium 23 Plus Servo drives



Commissioning using Lexium 23 CT software

Lexium 23 CT PC commissioning software : for rapid commissioning and easy configuration

The commissioning time for Lexium 23 Plus servo servo drives is considerably reduced using Lexium 23 CT PC software.

It is used for commissioning, parameter setting, diagnostics and maintenance.

It can also be used to install Lexium 23 Plus servo drives in existing installations, keeping downtime to a minimum.

Functions

Lexium 23 CT software includes the following functions:

- Auto-tuning
- Manual tuning
- Entry and display of parameters
- Oscilloscope function
- Fault diagnostics

Auto-tuning

The auto-tuning function can be activated with the Lexium 23 CT software in two ways:

□ Theoretical parameter setting: to calculate the gain parameters according to conditions selected by the user.

□ Dynamic parameter setting: for optimum control, calculating the gain parameters in real time, according to the behaviour of the machine.

Entry and display of parameters

The Lexium 23 CT software can be used to configure all the functions of a given operating mode.

The user interface of the Lexium 23 CT software enables quick, easy navigation. All the parameters can be displayed on a single graphic screen, which gives the experienced user a great deal of flexibility.

Frequency analysis (FFT)

The frequency analysis, based on the Fast Fourier Transform (FFT) algorithm, is used to diagnose noise and vibration in machines.

To carry out the FFT analysis, the motor records the behaviour of the axis in terms of current and speed. Once the movement has been executed, the Lexium 23 CT commissioning software analyses the resonance peaks and displays them on the oscilloscope screen.

It is possible to enter the gain as a numerical value, a variable or an expression in the gain parameter field.

Filters can be applied to reduce resonance.

Oscilloscope function

The Lexium 23 CT PC commissioning software provides an Oscilloscope function which can be used in two ways:

Realtime mode: to monitor the evolution of a value measured in real time

■ Precision mode: to capture a precise moment of the application This function records all the information before displaying it, which enables very precise information to be obtained and very fine tuning to be carried out.

Required configuration

The Lexium 23 CT software runs on a PC with the Microsoft Windows[®] 2000/XP/Vista operating systems. The servo drive is commissioned via the RS 232 serial link interface.

Downloading

The Lexium 23 CT PC commissioning software can be downloaded from our website www.schneider-electric.com.

BCH servo motors: page 14

Options

Motion control Lexium 23 Plus Servo drives

Main functions

Lexium 23 Plus servo drives feature numerous functions enabling them to be used in a wide range of motion control applications.

Main functions of Lexium 23 Plus servo drives

- Automatic recognition of the motor
- Filtering:
- Reduction of resonance
- □ Low pass filter for attenuation of high frequency disturbance
- Command smoothing
- Monitoring functions:
- □ Status monitoring, I/O monitoring
- □ Fault log, fault reset
- Monitoring of closed loop control, etc.

Tuning functions

- Manual mode (JOG) for position and speed
- Auto-tuning: This function is used to optimize application performance

Operating modes for the Lexium 23D version (activation/setting parameters of functions via the digital I/O) $\,$

Position control

In this mode position and speed control are carried out via a pulse train sent by an axis controller, such as a PLC, a motion controller or a numerical controller.

This mode is particularly suitable for the following applications:

- Material handling
- Cutting to length
- Packaging

Speed control

In this mode the Lexium 23 Plus servo drive is controlled with an axis controller with analog output. It is suitable for any application requiring high-performance speed control.

This mode is particularly suitable for the following applications:

- Winding
- Unwinding

Current regulation

Current regulation is required in applications in which servo motor torque control is crucial.

This mode is particularly suitable for the following applications:

- Printing
- Winding

Parameter switching

This function enables switching between three sets of parameters:

- Speed/position
- Speed/torque
- Torque/position

This function is specifically for machines with numerous manufacturing processes.

Other functions

- Speed limiting
- Torque limiting
- Encoder simulation (ESIM): control of speed, torque or frequency

Operating modes for the Lexium 23A version (activation/setting parameters of functions via the CANopen machine bus)

The following operating modes are available:

- Homing (in accordance with functional profile CiA DSP 402)
- Point-to-point mode (in accordance with functional profile CiADSP 402)
- Position gear mode
- Sync (cyclic)

For details of all the functions integrated in Lexium 23 Plus servo drives, please consult our website www.schneider-electric.com.

Motion control Lexium 23 Plus Servo drives

BCH servo motor/Lexium 23 Plus servo drive combinations Motor Servo drive Combination Motor inertia Power Inertia Nominal Maximum Maximum Nominal Servo drive Servo motor type indicated (without torque peak speed speed on rating brake) torque plate kW kgcm² Nm Nm rpm rpm Supply voltage, single phase: 200...255 V or three-phase: 170...255 V 50/60 Hz 0.1 0.037 0.32 0.96 5000 3000 LXM23eU01M3X BCH04010e2e1C Ultra low 0.2 0.177 0.64 1.92 5000 3000 LXM23eU02M3X BCH06010e2e1C Ultra low 0.3 8.17 2.86 8.59 2000 1000 LXM23eU04M3X BCH1301Me2e1C Medium 0.4 0.277 1.27 3.82 5000 3000 LXM23•U04M3X BCH0602O•2•1C Ultra low 0.4 0.68 1.27 3.82 5000 3000 LXM23•U04M3X BCH08010•2•1C Low 0.5 8.17 2.39 7.16 3000 2000 LXM23•U04M3X BCH1301N•2•1C Medium 0.6 17.19 1000 LXM23•U07M3X 8.41 5.73 2000 BCH1302Me2e1C Medium 0.75 2.39 7.16 5000 3000 LXM23eU07M3X BCH0802Oe2e1C 1.13 Low LXM23•U10M3X 0.9 11.18 8.59 25.78 2000 1000 BCH1303Me2e1C Medium 1 2.65 3.18 9.54 5000 3000 LXM23•U10M3X BCH10010e2e1C Low 1 11.18 4.77 14.32 3000 2000 LXM23•U10M3X BCH1302N•2•1C Medium 1.5 11.18 7.16 21.48 3000 2000 LXM23•U15M3X BCH1303N•2•1C Medium Three-phase supply voltage: 170...255 V 50/60 Hz 2 LXM23•U20M3X BCH1002O•2•1C 19.11 3000 4.45 5000 Low 6.37 2 14 59 26 65 LXM23eU20M3X BCH1304Ne2e1C 9 55 3000 2000 Medium 2 LXM23eU20M3X BCH1801Ne2e1C 34.58 9.55 26.65 3000 2000 High 3 54.95 14.32 42.96 3000 2000 LXM23eU30M3X BCH1802N+2+1C High 3 54.95 19.1 57.29 3000 1500 LXM23eU30M3X BCH1802Me2e1C High 3.5 16.71 50.31 LXM23eU45M3X BCH1803N•2•1C 54.8 3000 2000 High 4.5 77.75 28.65 71.62 3000 1500 LXM23eU45M3X BCH1803Me2e1C High 5.5 99.78 35.01 87.53 3000 1500 LXM23eU55M3X BCH1804Me2e1C Hiah 7.5 142.7 47.74 119.36 3000 1500 LXM23•U75M3X BCH1805Me2e1C Hiah References Example L Х М 2 3 Α U 0 1 М 3 Х Servo drive L Х м 2 3 A U 0 1 Μ 3 Х LXM = Lexium servo drive L Х 2 3 υ 0 3 Drive type Μ А 1 М х 23 = standard Interface L Х Μ 2 3 U 0 1 Μ 3 Х Α A = CANopen machine bus D = pulse/direction interface L Х Μ 2 3 М 3 х Power А U 0 1 **U01** = 0.1 kW **U02** = 0.2 kW **U04** = 0.4 kW **U07 =** 0.75 kW U05 = 0.5 kW U10 = 1 kW $U15 = 1.5 \, kW$ **U20** = 2 kW U30 = 3 kW **U45 =** 4.5 kW U55 = 5.5 kW **U75** = 7.5 kW Х U м Х Supply voltage L Μ 2 3 А 0 1 3 M3X = 200...240 V \sim single phase or three-phase Dimensions (overall in mm) Servo drives LXM 23 U20M3X U01M3X U07M3X •U45M3X U55M3X U75M3X •U10M3X U02M3X U30M3X •U04M3X U15M3X WxH 60 x 162 85 x 162 114 x 225 110 x 245 123 x 245 136 x 245 D 146 180 195 205 216.5

Motor starters: page 12

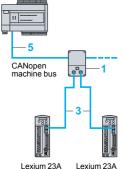
BCH servo motors: page 14

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Motion control Lexium 23 Plus Connection accessories

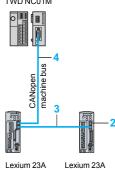
M238 logic controller

CANopen and CANmotion machine bus for Lexium 23 Plus servo drives



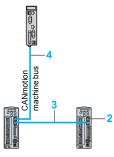
Example of architecture with control by M238 logic controller

Twido programmable controller + TWD NC01M



Example of architecture with control by Twido programmable controller

Lexium Controller LMC 20 or LMC 20A130•



Lexium 23A Lexium 23A Example of architecture with control by LMC Lexium Controller Lexium 23 Plus servo drives can be connected directly to the CANopen machine bus using an RJ45 connector.
To simplify daisy chain connection, each servo drive is equipped with two RJ45 connectors.
The communication function provides access to the servo drive's configuration, adjustment, control and monitoring functions.
Used with a Lexium Motion Controller, the CANmotion bus can be used to control motion for applications with up

to eight Lexium 23 Plus servo drives.

Connection accessor	ies (1)			
Description	Use	ltem no.	Reference	Weight kg
IP 20 CANopen tap 2 RJ45 ports	Tap-off from trunk cable for RJ45 cabling	1	VW3 CAN TAP2	0.480
Line terminator 120 Ω (equipped with 1 RJ45	Connection to the RJ45 connector	2	TCS CAR 013M120	0.009

connector)

Cordsets and cables (1)						
Description	Use		Item no.	Length	Reference	Weight
	From	То		m		kg
CANopen cordsets	VW3 CAN TAP2	LXM 23A servo drive	3	0.3	VW3 CAN CARR03	0.320
equipped with 2 RJ45 connectors	junction box LXM 23A servo drive			1	VW3 CAN CARR1	0.500
CANopen cordsets		LXM 23A servo drive	4	1	VW3 M3 805R010	_
equipped with one 9-way female SUB-D connector with integrated line terminator and one RJ45 connector	controller Lexium motion controller LMC 20, LMC 20A130●			3	VW3 M3 805R030	_
CANopen cables	PLC	VW3 CAN TAP2 junction box	5	50	TSX CAN CA 50	4.930
Standard cables, C€ marking				100	TSX CAN CA 100	8.800
Low smoke, zero halogen Flame retardant (IEC 60332-1)				300	TSX CAN CA 300	24.560
CANopen cables	PLC	VW3 CAN TAP2	5	50	TSX CAN CB 50	3.580
UL certification, C€ marking		junction box		100	TSX CAN CB 100	7.840
Flame retardant (IEC 60332-2)				300	TSX CAN CB 300	21.870
CANopen cables	PLC	VW3 CAN TAP2	5	50	TSX CAN CD 50	3.510
Cables for harsh environments		junction box		100	TSX CAN CD 100	7.770
(2) or mobile installations, CE marking Low smoke, zero halogen Flame retardant (IEC 60332-1)				300	TSX CAN CD 300	21.700

(1) For other CANopen machine bus connection accessories, please consult our website www.schneider-electric.com.

(2) Harsh environment:

- Resistance to hydrocarbons, industrial oils, detergents, solder splashes

- Relative humidity up to 100%

- Saline atmosphere

Significant temperature variations
 Operating temperature between - 10°C and + 70°C

Options:	Motor starters:	BCH servo motors:	
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Motion control Lexium 23 Plus Option: braking resistors for servo drives

Presentation

Internal braking resistor

A braking resistor is built into the servo drive to absorb the braking energy. If the DC bus voltage in the servo drive exceeds a specified value, this braking resistor is activated. The restored energy is converted into heat by the braking resistor.

It enables maximum braking torque.

External braking resistor

When the servo motor has to be braked frequently, an external braking resistor must be used to dissipate the excess braking energy. In this case, the internal braking resistor must be deactivated.

Several external braking resistors can be connected in parallel. The servo drive monitors the power dissipated in the braking resistor.

The degree of protection of the unit is IP 21.

Applications

Machines with high inertia, driving loads and machines with fast cycles.

References	;			
Ohmic value	Continuous power PPr	Peak energy (220 V) EPk	Reference	Weight
Ω	W	Ws		kg
40	400	4000	VW3 M7 111	0.930
20	1000	4000	VW3 M7 112	2.800

Note: The total continuous power dissipated in the external braking resistor(s) must be less than or equal to the nominal power of the Lexium 23 Plus servo drive (see page 8).

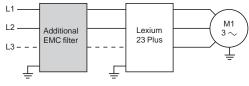
Servo drives:	
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Presentation, references

Motion control Lexium 23 Plus

Option: additional EMC input filters for servo drives



Lexium 23 Plus servo drive with additional EMC filter

Additional EMC input filters

Applications

Combined with Lexium 23 Plus servo drives, additional EMC input filters can be used to meet more stringent requirements and are designed to reduce conducted emissions on the line supply below the limits of standard IEC/EN 61800-3 edition 2 category C2 or C3 (EMC immunity and conducted and radiated EMC emissions).

The additional EMC filters have tapped holes for mounting in an enclosure.

Use according to the type of line supply

EMC filters can only be used on TN (neutral connection) and TT (neutral to earth) type systems.

Lexium 23 Plus servo drives cannot be used on IT (isolated or impedance earthed neutral) systems. Standard IEC/EN 61800-3, appendix D2.1, states that on IT systems, filters can cause permanent insulation monitors to operate in a random manner.

In addition, the effectiveness of additional filters on this type of system depends on the type of impedance between neutral and earth, and therefore cannot be predicted.

If a machine has to be installed on an IT system, an isolation transformer must be inserted in order to re-create a TT system on the secondary side.



Additional EMC filter VW3 A31 401

References				
For servo drive	Maximum servo mo length conforming		Reference	Weight
	EN 55011 class A Gr1	EN 55011 class A Gr2		
	IEC/EN 61800-3 category C2 (1) in environment 1	IEC/EN 61800-3 category C3 (1) in environment 2	_	
	m	m		kg
Single phase su	upply voltage			
LXM23•U01M3X LXM23•U02M3X LXM23•U04M3X	-	-	VW3 A31 401	0.600
LXM23•U07M3X LXM23•U10M3X LXM23•U15M3X	-	-	VW3 A31 403	0.775
Three-phase su	pply voltage			
LXM23•U07M3X LXM23•U10M3X LXM23•U15M3X LXM23•U20M3X LXM23•U30M3X	20	40	VW3 A31 404	0.900
LXM23•U45M3X LXM23•U55M3X	20	40	VW3 A31 406	1.350
LXM23eU75M3X	20	40	VW3 A31 407	3.150

(1) Standard IEC/EN 61800-3: EMC immunity and conducted and radiated EMC emissions: - Category C2 in environment 1: restricted distribution, for domestic use, sale conditional on the competence of the user and the distributor in the reduction of current harmonics. Category C3 in environment 2: industrial premises.

Servo drives:	Motor starters:	BCH servo motors:	
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			_

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Combinations

Motion control Lexium 23 Plus Motor starters







GV2 L14 + LC1 D09 LXM 23AU04M3X

Applications

The combinations listed below can be used to create a complete motor starter unit comprising a circuit breaker, a contactor and a Lexium 23 Plus servo drive.

The circuit-breaker provides protection against accidental short-circuits, disconnection and, if necessary, isolation.

The contactor turns on and manages any safety functions, as well as isolating the servo motor on stopping.

The servo drive controls the servo motor, provides protection against short-circuits between the servo drive and the servo motor and protects the motor cable against overloads. The overload protection is provided by the motor thermal protection of the servo drive.

fault and in

Motor starte	rs for Lexium 23	Plus ser	vo drives	
Servo drive		Circuit brea	aker	Contactor
Reference	Nominal power	Reference	Rating	Reference (1) (2)
	kW		А	
Single phase su	upply voltage: 200	255 V \sim 50	/60 Hz	
or three-phase	supply voltage: 170.	255 V \sim 5	50/60 Hz	
LXM 23eU01M3X	0.1	GV2 L10	6.3	LC1 K0610.
LXM 23eU02M3X	0.2	GV2 L10	6.3	LC1 K0610.
LXM 23eU04M3X	0.4	GV2 L14	10	LC1 D09ee
LXM 23eU07M3X	0.75	GV2 L14	10	LC1 D09••
LXM 23eU10M3X	1	GV2 L16	14	LC1 D1200
LXM 23eU15M3X	1.5	GV3 L22	25	LC1 D18.
LXM 23eU20M3X	2	GV3 L32	30	LC1 D32.
LXM 23eU30M3X	3	GV3 L32	30	LC1 D32.
LXM 23eU45M3X	4,5	GV3L65	60	LC1D65ee
LXM 23eU55M3X	5,5	GV3L65	60	LC1D65ee
LXM 23eU75M3X	7,5	NSE75HC (3)	75	LC1D80ee

(1) Composition of the contactors:

(1) Composition of the contract of the control of the control and protection components" catalogue.
(2) Replace •• with the control circuit voltage reference given in the table below:

	Volts \sim	24	48	110	220	230	240
LC1-K	50/60 Hz	B7	E7	F7	M7	P7	U7
	Volts \sim	24	48	110	220/230	230	230/240
LC1 D	50 Hz	B5	E5	F5	M5	P5	U5
	60 Hz	B6	E6	F6	M6	-	U6
	50/60 Hz	B7	E7	F7	M7	P7	U7

For other available voltages between 24 V and 660 V, or a DC control circuit, please contact our Customer Care Centre.

(3) Circuit breaker NSE75HC to be ordered under the reference number 35710.

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Combinations (continued)

Motion control Lexium 23 Plus

Motor starters Protection using fuses

÷ 4 R/L10 2 S/L20 4 T/L30 6	
÷ U/T1 V/T2 W/T3	

Motor starter with fuse protection

Protection usin	ng class J fuses (UL certification)
Servo drive		Fuse to be placed upstream
Reference	Nominal power	
	kW	А
Single phase supp	ly voltage: 200255	V \sim 50/60 Hz
or three-phase sup	oply voltage: 17025	5 V \sim 50/60 Hz
LXM 23eU01M3X	0.1	5
LXM 23eU02M3X	0.2	5
LXM 23eU04M3X	0.4	20
LXM 23eU07M3X	0.75	20
LXM 23eU10M3X	1	25
LXM 23eU15M3X	1.5	40
LXM 23eU20M3X	2	60
LXM 23eU30M3X	3	80
LXM 23eU45M3X	4.5	160
LXM 23eU55M3X	5.5	160
LXM 23eU75M3X	7.5	200

Servo drives:	
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Presentation

Motion control Lexium 23 Plus BCH servo motors



BCH servo motor range

Presentation

BCH servo motors are synchronous motors.

They are equipped as standard with a high resolution (20-bit) incremental encoder. They are therefore ideal for high performance applications such as material working, machine tools, etc.

The servo motors are available in six flange sizes: 40 mm, 60 mm, 80 mm, 100 mm, 130 mm and 180 mm.

They are available in a version with holding brake (see opposite page).

With the four types of motor inertia available, ranging from ultra low to high inertia, the servo motors can be used in a very wide variety of installations:

Ultra low inertia:

power between 0.1 kW and 0.4 kW, suitable for electronic equipment and small printing machinery.

Low inertia:

power between 0.4 kW and 2 kW, suitable for textile and packaging applications. Medium inertia:

power between 0.3 kW and 3 kW, suitable for material working and machine tool applications.

High inertia:

power between 2 kW and 7.5 kW, suitable for metal working and printing applications.

Examples of applications according to motor inertia type:

Type of	Inertia							
machine	Ultra low	Low	Medium	High				
Conveyors								
Packaging machines								
Printers								
Loaders/ unloaders								
X - Y tables								
Presses								
PCB drilling machines								
Electronic card testers								
Labelling machines								
Knitting and embroidery machines								
Special machines								
Winders/ unwinders								

Options

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Motion control Lexium 23 Plus BCH servo motors

References													
Example:	В	С	Н	0	4	0	1	0	0	2	Α	1	С
Servo motor BCH = three-phase servo motor	В	С	Н	0	4	0	1	0	0	2	A	1	С
Flange size 940 = 40 mm 960 = 60 mm 980 = 80 mm 100 = 100 mm 130 = 130 mm 180 = 180 mm	В	С	Η	0	4	0	1	0	0	2	A	1	С
Number of motor stages 1 = 1 stage (all flange sizes) 2 = 2 stages (with 60, 80, 100, 130 and 180 mm flanges) 3 = 3 stages (with 130 and 180 mm flanges) 4 = 4 stages (with 130 and 180 mm flanges) 5 = 5 stages (with 180 mm flange)	В	С	Η	0	4	0	1	0	0	2	A	1	С
Speed type ✔ = slow (1000/1500 rpm), (with 130 and 180 mm flanges) ♥ = medium (2500 rpm), (with 130 and 180 mm flanges) ♥ = fast (3000 rpm), (with 40, 60, 80 and 100 mm flanges)	В	С	Н	0	4	0	1	0	0	2	A	1	С
Shaft end 0 = smooth, IP 40 degree of protection 1 = keyed, IP 40 degree of protection 2 = smooth, IP 65 degree of protection 3 = keyed, IP 65 degree of protection	В	С	Н	0	4	0	1	0	0	2	A	1	С
Integrated encoder 2 = 20-bit high resolution incremental encoder	В	С	Н	0	4	0	1	0	0	2	A	1	С
Holding brake A = without brake F = with brake	В	С	Н	0	4	0	1	0	0	2	A	1	С
Connection 1 = flying leads (for BCH040…080 servo motors) or round connector (for BCH100…180 servo motors)	В	С	Н	0	4	0	1	0	0	2	A	1	С
Type of mounting C = mechanical	В	С	Н	0	4	0	1	0	0	2	A	1	С
Characteristics													
Servo motors	Witho	ut hold	ding bi	rake			W	ith hold	ling bra	ake			
	WxH	x D (1))			Weight	W	x H x D	(1)			۱	Weigh
	mm					kg	m	m					k
BCH0401	40 x 40	0 x 100	.6			0.500	40) x 40 x	136.6				0.8
BCH0601	60 x 60	0 x 105	.5			1.200	60) x 60 x	141.6				1.5
BCH0602	60 x 60	0 x 130	.7			1.600	60) x 60 x	166.8				2.0
BCH0801	80 x 80	0 x 112	.3			2.100	80) x 80 x	152.8				2.9
BCH0802	80 x 80	0 x 138	.3			3.000	80) x 80 x	178				3.8
BCH1001	100 x 1	100 x 1	53.5			4.300	10	00 x 100	x 192.5	5			4.7
BCH1002		100 x 1				6.200		00 x 100					7.2
BCH1301		130 x 1				6.800		30 x 130					8.2
BCH1302		130 x 1				7.000		30 x 130		5			8.4
BCH1303M		130 x 1				7.500		30 x 130					8.9
BCH1303N		130 x 1				7.500		30 x 130					8.9
BCH1304		130 x 1				7.800		30 x 130					9.2
BCH1801		180 x 1				13.500		30 x 180					17.5
		180 x 2	02.1			18.500	18	30 x 180	x 235.3	5			22.5
	180 x 1		00.4			40 500		10					
BCH1802 BCH1803N	180 x 1	180 x 2				18.500		30 x 180					22.5
	180 x ² 180 x ²		35.3			18.500 23.500 30.500	18	30 x 180 30 x 180 30 x 180	x 279.3	3			22.5 29.0 36.0

(1) D: dimensions of the casing (excluding shaft end)



Motion control Lexium 23 Plus BCH servo motors

Connection accessories

Designation	Description	Reference	Weight kg
Set of 3 terminal blocks	1 terminal block for power supply 1 terminal block for motor power supply 1 terminal block for braking resistor For mounting on drive side	VW3 M4 121	0.500
Connector for I/O interface	For mounting on drive side	VW3 M4 112	0.050
Screw terminal block	For I/O interface For mounting on drive side	VW3 M4 113	0.020
RS 232/USB converter	Equipped with: ■ One USB connector ■ One RJ 45 connector	VW3 M8 131	0.300

Connection cable				
Designation	Description	Cable length	Reference	Weight
		m		kg
Connection cable for VW3 M8 131 converter	Equipped with an RJ 45 connector at each end. To connect the VW3 M8 131 converter to the servo drive.	2	490 NTW 00002	-
Connectors for power cable				
Description	For servo motor	ltem no.	Reference	Weight kg
Connector for motor without holding brake	BCH 04010•2A1C BCH 06010•2A1C BCH 06020•2A1C BCH 08010•2A1C BCH 08010•2A1C BCH 08020•2A1C	1	VW3 M5 111	0.030
• •				

	Description	For serv
	Connector for motor without holding brake	BCH 040 BCH 060 BCH 060 BCH 080 BCH 080
▲ ▲ — 1	Connector for motor with holding brake	BCH 060 BCH 060 BCH 080 BCH 080
	Round connectors for motor with or without holding brake	BCH 100 BCH 100 BCH 130 BCH 130 BCH 130 BCH 130 BCH 130 BCH 130 BCH 180 BCH 180 BCH 180 BCH 180

0.030
0.180
0.180
0.300
0.500
_

Connectors for encoder cable				
Description	For servo motor	Item no.	Reference	Weight kg
Connector for motor with connection via stripped cable	BCH 0401O•2•1C BCH 0601O•2•1C BCH 0602O•2•1C BCH 0801O•2•1C BCH 0802O•2•1C	2	VW3 M8 121	0.800
Connector for motor equipped with a round connector	BCH 1001O•2•1C BCH 1002O•2•1C BCH 1301M•2•1C BCH 1301M•2•1C BCH 1302N•2•1C BCH 1302N•2•1C BCH 1302N•2•1C BCH 1303N•2•1C BCH 1303N•2•1C BCH 1804N•2•1C BCH 1802N•2•1C BCH 1803N•2•1C BCH 1803N•2•1C BCH 1803N•2•1C BCH 1803N•2•1C BCH 1803N•2•1C BCH 1803N•2•1C BCH 1805M•2•1C	2	VW3 M8 122	0.800

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Motion control Lexium 23 Plus BCH servo motors

Connection accessories

Connection components (continued)



Description	From servo motor	To servo drive	Composition	Length of cable	Reference	Weight
				m		kg
Cordsets equipped	BCH04010e2A1C	LXM23eU01M3X	4 x 0.82 mm ²	3	VW3 M5 111R30	0.20
vith a plastic connector servo motor end)	BCH0601Oe2A1C	LXM23eU02M3X		5	VW3 M5 111R50	0.35
and one end with flying leads	BCH0602Oe2A1C	LXM23eU04M3X				
servo drive end).	BCH0801Oe2A1C	LXM23eU04M3X				
Nithout holding brake	BCH0802Oe2A1C	LXM23eU07M3X	-			
Cordsets equipped	BCH04010e2F1C	LXM23eU01M3X	6 x 0.82 mm ²	3	VW3 M5 112R30	0.20
with a plastic connector	BCH06010e2F1C	LXM23eU02M3X	•	5	VW3 M5 112R50	0.35
servo motor end)	BCH0602Oe2F1C	LXM23eU04M3X	-			
and one end with flying leads servo drive end).	BCH0801Oe2F1C	LXM23eU04M3X	-			
With holding brake	BCH0802O•2F1C					
Cordsets equipped	BCH10010•2A1C		4 x 1.3 mm ²	3	VW3 M5 121R30	0.35
with a round connector	BCH1301Me2A1C			5	VW3 M5 121R50	0.60
servo motor end)				5	V VV3 IVI3 121K30	0.00
and one end with flying leads	BCH1301Ne2A1C		-			
servo drive end).	BCH1302Me2A1C		-			
Nithout holding brake	BCH1302Ne2A1C					
	BCH1303Me2A1C		-			
	BCH1303Ne2A1C	LXM23eU15M3X				
	BCH1002Oe2A1C	LXM23eU20M3X	4 x 2.1 mm ²	3	VW3 M5 122R30	0.45
	BCH1304Ne2A1C	LXM23eU20M3X	-	5	VW3 M5 122R50	0.75
	BCH1801Ne2A1C	LXM23eU20M3X	4 x 3.3 mm ²	3	VW3 M5 123R30	0.76
	BCH1802Ne2A1C	LXM23eU30M3X		5	VW3 M5 123R50	1.75
	BCH1802Me2A1C		-			
	BCH1803M•2A1C		-			
	BCH1803N•2A1C		4 x 8.4 mm ²	3	VW3 M5 124R30	1.00
	DOITIOUSINEZATO		4 × 0.4 mm	5	VW3 M5 124R50	1.20
			0	-		
Cordsets equipped with a round connector	BCH10010•2F1C		6 x 1.3 mm ²	3	VW3 M5 131R30	0.35
servo motor end)	BCH1301Me2F1C			5	VW3 M5 131R50	0.60
nd one end with flying leads servo drive end). Vith holding brake	BCH1301Ne2F1C					
	BCH1302Me2F1C					
	BCH1302Ne2F1C	LXM23eU10M3X				
	BCH1303Me2F1C	LXM23eU10M3X				
	BCH1303Ne2F1C	LXM23eU15M3X				
	BCH1002Oe2F1C	LXM23eU20M3X	6 x 2.1 mm ²	3	VW3 M5 132R30	0.75
	BCH1304Ne2F1C	LXM23eU20M3X	-	5	VW3 M5 132R50	1.25
	BCH1801Ne2F1C	LXM23eU20M3X	6 x 3.3 mm ²	3	VW3 M5 133R30	0.76
	BCH1802Me2F1C	LXM23eU30M3X		5	VW3 M5 133R50	1.95
	BCH1802N•2F1C					
	BCH1803N•2F1C		-			
	BCH1803Me2F1C		6 x 8.4 mm ²	3	VW3 M5 134R30	
	BCH 1003WIOZF IC		0 X 0.4 11111	-		
				5	VW3 M5 134R50	
Encoder cordsets						
Cordsets equipped	BCH04010e2e1C	LXM23eU01M3X	10 x 0.13 mm ²	3	VW3 M8 121R30	1.00
with a plastic connector	BCH060100201C			5	VW3 M8 121R50	1.20
at each end				5	4 445 INIO 121R3U	1.20
	BCH0602O•2•1C					
	BCH08010e2e1C					
	BCH0802Oe2e1C					
Cordsets equipped	BCH1001Oe2e1C	LXM23eU10M3X	10 x 0.13 mm ²	3	VW3 M8 122R30	1.00
vith a round connector servo motor end)	BCH1002Oe2e1C	LXM23eU20M3X		5	VW3 M8 122R50	1.20
and a plastic connector	BCH1301Me2e1C	LXM23eU04M3X				
servo drive end)	BCH1301Ne2e1C	LXM23eU04M3X	-			
,	BCH1302Me2e1C	LXM23eU07M3X	•			
	BCH1302Ne2e1C		-			
	BCH1303M•2•1C					
	BCH1303Ne2e1C					
			-			
	BCH1304Ne2e1C		-			
	BCH1801N•2•1C					
	BCH1802Me2e1C					
	BCH1802Ne2e1C					
	BCH1803Me2e1C	LXM23eU45M3X	-			
	BCH1803Ne2e1C	LXM23eU45M3X				
	BCH1804Me2e1C	LXM23eU75M3X	-			

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